

Package ‘GLmom’

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Type Package

Title Generalized L-Moments Estimation for Extreme Value Distributions

Version 2.0.1

Description Provides generalized L-moments estimation methods for the generalized extreme value ('GEV') distribution. Implements both stationary 'GEV' and non-stationary 'GEV11' models where location and scale parameters vary with time. Includes various penalty functions (Martins-Stedinger, Park, Cannon, Coles-Dixon) for shape parameter regularization. Also provides model averaging estimation ('ma.gev') that combines MLE and L-moment methods with multiple weighting schemes for robust high quantile estimation. The 'GLME' methodology is described in Shin et al. (2025a) <[doi:10.48550/arXiv.2512.20385](https://doi.org/10.48550/arXiv.2512.20385)>. The non-stationary L-moment method is based on Shin et al. (2025b) <[doi:10.1007/s42952-025-00325-3](https://doi.org/10.1007/s42952-025-00325-3)>. The model averaging method is described in Shin et al. (2026) <[doi:10.1007/s00477-025-03167-x](https://doi.org/10.1007/s00477-025-03167-x)>. See also Hosking (1990) <[doi:10.1111/j.2517-6161.1990.tb01775.x](https://doi.org/10.1111/j.2517-6161.1990.tb01775.x)> for L-moments theory and Martins and Stedinger (2000) <[doi:10.1029/1999WR900330](https://doi.org/10.1029/1999WR900330)> for penalized likelihood methods.

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URL <https://github.com/sygstat/GLmom>

BugReports <https://github.com/sygstat/GLmom/issues>

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bangkok	<i>Bangkok Maximum Rainfall Data</i>
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Description

Annual maximum daily rainfall data from Bangkok, Thailand. This dataset is used for demonstrating model averaging methods for high quantile estimation in extreme value analysis.

Usage

bangkok

Format

A data frame with 58 rows and 5 columns:

X1 Annual maximum daily rainfall in mm (numeric)

X2 2nd largest annual daily rainfall in mm (numeric)

X3 3rd largest annual daily rainfall in mm (numeric)

X4 4th largest annual daily rainfall in mm (numeric)

X5 5th largest annual daily rainfall in mm (numeric)

Source

Thai Meteorological Department (TMD; <https://www.tmd.go.th>)

References

Shin, Y., Shin, Y., & Park, J. S. (2026). Model averaging with mixed criteria for estimating high quantiles of extreme values: Application to heavy rainfall. *Stochastic Environmental Research and Risk Assessment*, 40(2), 47. doi: [10.1007/s0047702503167x](https://doi.org/10.1007/s0047702503167x)

Examples

```
data(bangkok)
head(bangkok)

# Estimate high quantiles using model averaging
result <- ma.gev(bangkok$X1, quant = c(0.99, 0.995))
print(result$qua.ma)
```

gado.prop_11

Comprehensive Non-stationary GEV Estimation (deprecated)

Description

Estimates parameters of a non-stationary GEV distribution using multiple methods: Weighted Least Squares (WLS), GN16 method, and the proposed L-moment method from Shin et al. (2025, J. Korean Stat. Soc.).

As of GLmom v2.0.0 this function is deprecated: it was renamed to [lme.gev11](#) (for the proposed method), and the auxiliary methods are available as [strup.gev11](#) and [GN16.gev11](#). This wrapper reassembles the v1.x output format from those functions and will be removed in a future release.

Usage

```
gado.prop_11(xdat, ntry = 20, ftol = 1e-06)
```

Arguments

<code>xdat</code>	A numeric vector of data to be fitted.
<code>ntry</code>	Number of attempts for optimization (default 20).
<code>ftol</code>	Function tolerance for optimization (default 1e-6).

Value

A list containing:

- `para.prop` - L-moment based estimates (proposed method).
- `para.gado` - GN16 method estimates.
- `para.wls` - Weighted least squares estimates.
- `strup.org` - Original non-stationary WLSE by Strup method.
- `lme.sta` - Stationary L-moment estimates.

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Shin, Y., Shin, Y. & Park, J.-S. (2025). Building nonstationary extreme value model using L-moments. Journal of the Korean Statistical Society, 54, 947-970. doi: [10.1007/s42952025003253](https://doi.org/10.1007/s42952025003253)

See Also

[lme.gev11](#) for the recommended interface, [strup.gev11](#), [GN16.gev11](#), [glme.gev11](#) for the full GLME method, [nsgev](#) for the simple interface.

Examples

```
data(PhliuAgromet)
# deprecated wrapper; suppressWarnings() silences the deprecation notice
result <- suppressWarnings(gado.prop_11(PhliuAgromet$prec, ntry = 5))
print(result$para.prop)
print(result$lme.sta)
```

glme.gev

*Generalized L-moments estimation for generalized extreme value distribution***Description**

This function estimates the parameters of the Generalized Extreme Value distribution by the generalized method of L-moment estimation (GLME), which minimizes the generalized L-moment distance plus a penalty (preference) function on the shape parameter.

Usage

```
glme.gev(
  xdat,
  ntry = 5,
  pen = "beta",
  pen.choice = 1,
  mu = -0.5,
  std = 0.2,
  p = 6,
  c1 = 3,
  c2 = 1,
  c0 = 0.35,
  q = NULL,
  show = FALSE,
  method = "BFGS",
  maxit = 70,
  abstol = 1e-05
)
```

Arguments

xdat	A numeric vector of data to be fitted.
ntry	Number of attempts for parameter estimation (default 5). Higher values increase the chance of finding the global optimum by trying different initial conditions.
pen	Type of penalty function: Choose among "norm", "beta" (default), "ms", "park", "cannon", "cd", and "no" (without penalty function).
pen.choice	Choice number of penalty function specifying hyperparameters (default 1). For "beta": 1-6 correspond to (p, c1, c2) = (6,3,1), (6,5,2), (6,7,3), (2,3,0.5), (2,5,1), (2,7,1.5). For "norm": 1-4 correspond to (mu, std) = (-0.5,0.25), (-0.5,0.15), (-0.6,0.25), (-0.6,0.15). Set pen.choice=NULL to use the hyperparameters given by p, c1, c2 (beta) or mu, std (norm) directly.
mu	Mean hyperparameter for "norm" penalty function (default -0.5).
std	Standard deviation hyperparameter for "norm" penalty function (default 0.2).
p	Shape hyperparameter for "beta" penalty function (default 6).

c1	Scaling hyperparameter for "beta" penalty function (default 3).
c2	Upper limit hyperparameter for "beta" penalty function (default 1).
c0	Half-width of the adaptive beta penalty support (default 0.35).
q	Optional fixed second shape parameter for the beta penalty. If given, the beta penalty support is fixed instead of data-adaptive.
show	If TRUE, prints the objective value and parameters of each try.
method	Optimization method passed to <code>optim</code> (default "BFGS").
maxit	Maximum number of iterations for <code>optim</code> (default 70).
abstol	Absolute and relative convergence tolerance for <code>optim</code> (default 1e-5).

Details

The equations for the L-moments for LME of the GEVD are

$$\underline{\lambda} - \underline{1} = \underline{0},$$

where $\underline{\lambda} = (\lambda_1, \lambda_2, \lambda_3)^t$ and $\underline{1} = (l_1, l_2, l_3)^t$. Next, we define the generalized L-moments distance (GLD) as;

$$(\underline{\lambda} - \underline{1})^t V^{-1} (\underline{\lambda} - \underline{1}),$$

where V is the variance-covariance matrix of the sample L-moments up to the third order.

Value

The `glme.gev` function returns a list containing the following elements:

- `para.glme` - The estimated parameters of the Generalized Extreme Value distribution.
- `para.lme` - The L-moment estimates of the parameters.
- `nllh.glme` - The penalized negative log-likelihood of the GLME solution.
- `convergence` - 0 if the optimization converged, 5 otherwise.
- `pen, pen_pen.choice` - The penalization method (and choice) used.
- `p_q` - (for beta penalty) The p and q values used.
- `c1_c2, c0_c1_c2` - (for beta penalty) The hyperparameters used.
- `mu_std` - (for norm penalty) The mu and std values used.
- `covinv.lmom` - The inverse of the covariance matrix of the L-moments.
- `lcovdet` - The log determinant of the covariance matrix.
- `data` - The input data (used by the plot method).

The object has class "glme"; see [GLmom-methods](#).

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Shin, Y., Shin, Y., Park, J. & Park, J.-S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi: [10.48550/arXiv.2512.20385](https://doi.org/10.48550/arXiv.2512.20385)

See Also

[glme.gev11](#) for non-stationary GEV estimation, [ma.gev](#) for model averaging estimation, [glme.like](#) for the objective function, [quagev.NS](#) for quantile computation.

Examples

```
# Load example heavy-rainfall data
data(haenam)
x <- haenam$X1

# Estimate GEV parameters using beta penalty (default)
result <- glme.gev(x, ntry = 5)
print(result$para.glme)

# Using Martins-Stedinger penalty
result_ms <- glme.gev(x, ntry = 5, pen = "ms")
print(result_ms$para.glme)
```

glme.gev11

Generalized L-moments estimation for non-stationary GEV11 model

Description

This function estimates parameters of the non-stationary GEV11 model where $\mu(t) = \mu_0 + \mu_1 \cdot t$ and $\sigma(t) = \exp(\sigma_0 + \sigma_1 \cdot t)$, by the generalized method of L-moment estimation (GLME).

Starting from the WLS pre-estimate of [strup.gev11](#), the penalized objective (generalized L-moment distance based on the asymptotic covariance of the sample L-moments, plus penalty) is minimized over (μ_0, σ_0, ξ) with μ_1 and σ_1 held at their pre-estimated values. With `pen="no"` the result equals the pure L-moment method [lme.gev11](#) of Shin et al. (2025b).

Usage

```
glme.gev11(
  xdat,
  ntry = 5,
  ftol = 1e-06,
  opt.choose = "nllh",
  pen = "beta",
  pen.choice = 1,
```

```

mu = -0.55,
std = 0.2,
p = 6,
c1 = 5,
c2 = 2,
c0 = 0.35,
q = NULL,
show = FALSE,
init.rob = TRUE,
glme.pre = NULL
)

```

Arguments

xdat	A numeric vector of data to be fitted.
ntry	Number of attempts for parameter estimation (default 5).
ftol	Tolerance for convergence (default 1e-6).
opt.choose	Selection criterion among the multi-start solutions: "nllh" (default, penalized negative log-likelihood) or "gof" (goodness-of-fit by the number-of-exceedances measure).
pen	Type of penalty function: "norm", "beta" (default), "ms", "park", "cannon", "cd", or "no".
pen.choice	Choice number for penalty hyperparameters (default 1). See glme.gev for the preset values. Set to NULL to use p, c1, c2 (beta) or mu, std (norm) directly.
mu	Mean for normal penalty (default -0.55).
std	Std for normal penalty (default 0.2).
p	Shape for beta penalty (default 6).
c1	Scaling for beta penalty (default 5).
c2	Limit for beta penalty (default 2).
c0	Half-width of the adaptive beta penalty support (default 0.35).
q	Optional fixed second shape parameter for the beta penalty.
show	If TRUE, prints the objective value of each try.
init.rob	Use robust regression for the WLS initialization (default TRUE).
glme.pre	Deprecated (ignored). The WLS pre-estimate is always used.

Value

A list containing:

- para.glme - Proposed GLME estimates (mu0, mu1, sigma0, sigma1, xi).
- nllh.glme - Penalized negative log-likelihood of the solution.
- convergence - 0 if converged, 5 otherwise.
- pen, pen_pen.choice - Penalty method (and choice) used.

- `p_q`, `c1_c2`, `c0_c1_c2` - (for beta) hyperparameters used.
- `mu_std` - (for norm) hyperparameters used.
- `strup.org` - WLSE by the Strupczewski method (`strup.para`).
- `para.wls` - Modified WLS estimates (`strup.mdfy`).
- `para.gado` - GN16 method estimates.
- `lme.sta` - Stationary L-moment estimates.
- `para.lme` - Pure L-moment estimates; returned only when `pen="no"` (then identical to `para.glme`). For other penalties use [lme.gev11](#) directly.
- `precis` - (only when `pen="no"`) precision of the L-moment equation solution.
- `data` - The input data (used by the `plot` method).

The object has class `"glme11"`; see [GLmom-methods](#).

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

- Shin, Y., Shin, Y., Park, J. & Park, J.-S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi: [10.48550/arXiv.2512.20385](#)
- Shin, Y., Shin, Y. & Park, J.-S. (2025). Building nonstationary extreme value model using L-moments. Journal of the Korean Statistical Society, 54, 947-970. doi: [10.1007/s42952025003253](#)

See Also

[glme.gev](#) for stationary GEV estimation, [lme.gev11](#) for the pure L-moment method (no penalty), [strup.gev11](#) for the WLS pre-estimation, [GN16.gev11](#) for the GN16 method, [quagev.NS](#) for non-stationary quantile computation.

Examples

```
data(PhliuAgromet)
x <- PhliuAgromet$prec

# Estimate non-stationary GEV11 parameters
result <- glme.gev11(x, ntry = 5)
print(result$para.glme) # Proposed GLME estimates
```

glme.like	<i>Calculate the likelihood for Generalized L-moments estimation of GEV distribution</i>
-----------	--

Description

This function calculates the likelihood (or more precisely, a penalized negative log-likelihood) for the Generalized L-moments estimation of the Generalized Extreme Value (GEV) distribution.

Usage

```
glme.like(
  par,
  xdat = xdat,
  slmgev = slmgev,
  covinv = covinv,
  lcovdet = lcovdet,
  mu = mu,
  std = std,
  lme = lme,
  pen = pen,
  p = p,
  c1 = c1,
  c2 = c2,
  c0 = 0.35,
  q = NULL
)
```

Arguments

par	A vector of GEV parameters (location, scale, shape).
xdat	A numeric vector of data.
slmgev	Sample L-moments of the data.
covinv	Inverse of the covariance matrix of the sample L-moments.
lcovdet	Log determinant of the covariance matrix.
mu	Mean for the normal penalization (used when pen='norm').
std	Standard deviation for the normal penalization (used when pen='norm').
lme	L-moment estimates of the parameters.
pen	Penalization method: 'norm', 'beta', 'ms', 'park', 'cannon', 'cd', or 'no'.
p	Shape parameter for beta penalty.
c1	Scaling parameter for beta penalty.
c2	Upper limit parameter for beta penalty.
c0	Half-width of the adaptive beta penalty support (default 0.35).
q	Optional fixed second shape parameter for the beta penalty.

Details

The function performs the following steps: 1. Checks if the parameters are within valid ranges. 2. Calculates the expected L-moments based on the current parameters. 3. Computes the difference between expected and sample L-moments. 4. Calculates the generalized L-moments distance. 5. Applies a penalization term based on the specified method. 6. Returns the sum of the L-moments distance and the penalization term.

Value

A numeric value representing the penalized negative log-likelihood. A lower value indicates a better fit.

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Shin, Y., Shin, Y., Park, J. & Park, J.-S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi: [10.48550/arXiv.2512.20385](https://doi.org/10.48550/arXiv.2512.20385)

See Also

[glme.gev](#) which calls this function for optimization.

Examples

```
data(haenam)
x <- haenam$X1
slm <- lmomco::lmoms(x, nmom = 3)
cov_mat <- lmomco::lmoms.cov(x, nmom = 3)
lme_par <- lmomco::pargev(slm)$para
glme.like(par = lme_par, xdat = x, slmgev = slm,
           covinv = solve(cov_mat), lcovdet = log(det(cov_mat)),
           mu = -0.5, std = 0.2, lme = lme_par, pen = "beta",
           p = 6, c1 = 3, c2 = 1)
```

Description

The estimation functions return classed objects: `glme.gev` returns an object of class "glme", `glme.gev11` of class "glme11", `lme.gev11` of class "lme11", and `ma.gev` of class "magev". The objects remain ordinary lists, so all documented fields (e.g., `$para.glme`) stay accessible as before.

`print` shows the parameter estimates and the penalty settings; `summary` additionally reports the auxiliary estimates stored in the object; `plot` draws a quantile-quantile diagnostic: against the fitted GEV distribution for "glme", on the standard Gumbel scale (after the transformation of Eq. 8 in the manuscript) for "glme11" and "lme11", and via `magev.qqplot` for "magev".

Usage

```
## S3 method for class 'glme'
print(x, ...)

## S3 method for class 'glme'
summary(object, ...)

## S3 method for class 'glme'
plot(x, ...)

## S3 method for class 'glme11'
print(x, ...)

## S3 method for class 'glme11'
summary(object, ...)

## S3 method for class 'glme11'
plot(x, ...)

## S3 method for class 'lme11'
print(x, ...)

## S3 method for class 'lme11'
summary(object, ...)

## S3 method for class 'lme11'
plot(x, ...)

## S3 method for class 'magev'
print(x, ...)

## S3 method for class 'magev'
summary(object, ...)

## S3 method for class 'magev'
plot(x, ...)
```

Arguments

`x`, object A fitted object.
`...` Further arguments passed to plotting functions; ignored by `print` and `summary`.

Value

`x` (or object), invisibly.

Examples

```
data(haenam)
fit <- glme.gev(haenam$X1)
fit
summary(fit)
plot(fit)
```

GN16.gev11

GN16 estimation for the non-stationary GEV11 model

Description

Estimates the parameters of the non-stationary GEV11 model by the quantile-based GN16 method (Gilleland and Katz, 2016; as adapted in Shin et al., 2025b), with both the original and the modified specification returned.

Usage

```
GN16.gev11(xdat, rob = FALSE)
```

Arguments

`xdat` A numeric vector of data to be fitted.
`rob` If TRUE, uses robust regression in the internal steps (default FALSE).

Value

A list containing:

- `para.gado.org` - Original GN16 estimates (`mu0`, `mu1`, `sigma0`, `sigma1`, `xi`).
- `para.gado.mdfy` - Modified GN16 estimates.

Author(s)

Yonggwan Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

- Gilleland, E. & Katz, R. W. (2016). extRemes 2.0: An extreme value analysis package in R. *Journal of Statistical Software*, 72(8), 1-39.
- Shin, Y., Shin, Y. & Park, J.-S. (2025). Building nonstationary extreme value model using L-moments. *Journal of the Korean Statistical Society*, 54, 947-970. doi: [10.1007/s42952025003253](https://doi.org/10.1007/s42952025003253)

See Also

[glme.gev11](#), [lme.gev11](#), [strup.gev11](#).

Examples

```
data(PhliuAgromet)
result <- GN16.gev11(PhliuAgromet$prec)
print(result$para.gado.org)
```

haenam

Haenam Maximum Rainfall Data

Description

Annual maximum daily rainfall data from Haenam, South Korea. This dataset is used for demonstrating model averaging methods for high quantile estimation in extreme value analysis.

Usage

haenam

Format

A data frame with 52 rows and 2 columns:

- year** Year of observation (integer, 1971-2022)
- X1** Annual maximum daily rainfall in mm (numeric)

Source

Korea Meteorological Administration (KMA; <https://www.weather.go.kr>)

References

- Shin, Y., Shin, Y., & Park, J. S. (2026). Model averaging with mixed criteria for estimating high quantiles of extreme values: Application to heavy rainfall. *Stochastic Environmental Research and Risk Assessment*, 40(2), 47. doi: [10.1007/s0047702503167x](https://doi.org/10.1007/s0047702503167x)

Examples

```
data(haenam)
head(haenam)

# Estimate high quantiles using model averaging
result <- ma.gev(haenam$X1, quant = c(0.98, 0.99, 0.995))
print(result$qua.ma)
```

init.glme	<i>Initialize starting values for GLME optimization</i>
-----------	---

Description

Generates multiple starting parameter sets for multi-start optimization in GLME estimation, for both the stationary GEV (model="gev00") and the non-stationary GEV11 (model="gev11"). Uses L-moment estimates as a base and adds random perturbations.

For model="gev11" the second column is returned on the log scale (matching sigma0 of the GEV11 parameterization), and when pretheta is supplied the first candidate is a perturbation of the pre-estimate.

Usage

```
init.glme(
  data = NULL,
  ntry = NULL,
  model = "gev00",
  pretheta = NULL,
  xdat = NULL
)
```

Arguments

data	A numeric vector of data to be fitted.
ntry	Number of initial parameter sets to generate (minimum 2).
model	Either "gev00" (stationary, default) or "gev11".
pretheta	Optional pre-estimate (mu0, mu1, sigma0, sigma1, xi) used for the first candidate when model="gev11".
xdat	Deprecated alias of data (v1.x compatibility).

Value

A matrix with ntry rows and 3 columns, where each row is a candidate starting point for optimization.

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

See Also

[glme.gev](#), [glme.gev11](#) which use this function internally.

Examples

```
data(haenam)
inits <- init.glme(haenam$X1, ntry = 5)
print(inits)
```

lme.gev11

L-moment parameter estimation for the non-stationary GEV11 model

Description

Estimates the parameters of the non-stationary GEV11 model ($\mu(t) = \mu_0 + \mu_1 t$, $\sigma(t) = \exp(\sigma_0 + \sigma_1 t)$, constant ξ) by the pure L-moment method of Shin et al. (2025b, JKSS). Starting from the WLS pre-estimate of [strup.gev11](#), the three L-moment equations (matching the sample L-moments of the Gumbel-transformed data with the population L-moments of the standard Gumbel distribution) are solved by Broyden's method for (μ_0, σ_0, ξ) , and the best solution is chosen by a goodness-of-fit measure.

This function replaces [gado.prop_11](#) of GLmom v1.x (renamed in v2.0.0, with slightly changed input/output). It is also equivalent to `glme.gev11(xdat, pen="no")`.

Usage

```
lme.gev11(xdat, ntry = 5, ftol = 1e-05, show = FALSE)
```

Arguments

xdat	A numeric vector of data to be fitted.
ntry	Number of attempts (initial points) for the nonlinear solver (default 5).
ftol	Function tolerance for the solver (default 1e-5).
show	If TRUE, prints the precision and parameters of each try.

Value

A list containing:

- lme.gev11 - The L-moment estimates (μ_0 , μ_1 , σ_0 , σ_1 , ξ). If no solution is found, the WLS pre-estimate is returned.
- precis - Precision (mean absolute residual of the L-moment equations) of the selected solution.
- data - The input data (used by the plot method).

The object has class "lme11"; see [GLmom-methods](#).

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Shin, Y., Shin, Y. & Park, J.-S. (2025). Building nonstationary extreme value model using L-moments. Journal of the Korean Statistical Society, 54, 947-970. doi: [10.1007/s42952025003253](https://doi.org/10.1007/s42952025003253)

See Also

[glme.gev11](#) for the penalized (GLME) version, [strup.gev11](#) for the WLS pre-estimation, [GN16.gev11](#) for the GN16 method, [nsgev](#) and [gado.prop_11](#) for the v1.x compatibility wrappers.

Examples

```
data(PhliuAgromet)
result <- lme.gev11(PhliuAgromet$prec, ntry = 5)
print(result$lme.gev11)
```

ma.gev

Model Averaging for GEV High Quantile Estimation

Description

This function estimates high quantiles of the Generalized Extreme Value (GEV) distribution using model averaging with mixed criteria. It combines Maximum Likelihood Estimation (MLE) and L-moment Estimation (LME) to construct candidate submodels and assign weights effectively.

Usage

```
ma.gev(
  data = NULL,
  quant = c(0.98, 0.99, 0.995),
  weight = "like1",
  numk = 12,
  B = 200,
  varcom = TRUE,
  trim = 0,
  fig = FALSE,
  bma = FALSE,
  pen = "norm",
  CD = FALSE,
  remle = FALSE
)
```

Arguments

data	A numeric vector of data to be fitted (e.g., annual maxima).
quant	The probabilities corresponding to high quantiles to be estimated. Default is <code>c(0.98, 0.99, 0.995)</code> .
weight	The weighting method name. Options are: • 'like', 'like0', 'like1' (default): Likelihood-based weights (AIC) • 'gLd', 'gLd0', 'gLd1', 'gLd2': Generalized L-moment distance weights • 'med', 'med1', 'med2': Median-based weights • 'cvt': Conventional AIC weights Variants with numbers indicate left trimming level (0, 1, or 2).
numk	The number of candidate submodels K. Default is 12.
B	The number of bootstrap samples. Default is 200.
varcom	Logical. Whether to compute variance of quantile estimates. Default is TRUE.
trim	The number of left trimming for L-moments. Usually 0 (default), 1, or 2.
fig	Logical. Whether to produce diagnostic plots. Default is FALSE.
bma	Logical. Whether to use Bayesian Model Averaging. Default is FALSE.
pen	Penalty type for BMA prior: 'norm' (normal, default) or 'beta'.
CD	Logical. Whether to compute Coles-Dixon penalized MLE. Default is FALSE.
remle	Logical. Whether to compute restricted MLE. Default is FALSE.

Details

The model averaging approach works as follows:

1. MLE and LME of GEV parameters are computed
2. K candidate shape parameters (ξ) are selected from profile likelihood CI
3. For each candidate ξ , MLE with fixed ξ is computed
4. Weights are assigned based on the selected method
5. Final quantile estimates are weighted averages across submodels

The weighting schemes include:

- 'like': AIC-based weights using likelihood with fixed ξ
- 'gLd': Weights based on generalized L-moment distance
- 'med': Weights based on median and L-moment distance
- 'cvt': Conventional AIC weights

When `bma=TRUE`, Bayesian model averaging is applied with prior specified by `pen`.

Value

A list containing:

- mle.hosking - MLE estimates in Hosking style (mu, sigma, xi)
- qua.mle - Quantile estimates from MLE
- mle.cov3 - Covariance matrix of MLE (3x3)
- qua.se.mle.delta - Standard errors of MLE quantiles (delta method)
- lme - L-moment estimates (mu, sigma, xi)
- lme.cov3 - Covariance matrix of LME (bootstrap)
- qua.lme - Quantile estimates from LME
- qua.se.lme.boots - Standard errors of LME quantiles (bootstrap)
- qua.ma - Model-averaged quantile estimates
- w.ma - Weights used for model averaging
- fixw.se.ma - Asymptotic SE under fixed weights
- ranw.se.ma - Asymptotic SE under random weights
- surr - Surrogate model parameters (mu, sigma, xi)
- pick_xi - Selected xi values for K submodels
- qua.bma - (if bma=TRUE) BMA quantile estimates
- w.bma - (if bma=TRUE) BMA weights
- mle.CD - (if CD=TRUE) Coles-Dixon penalized MLE
- qua.CD - (if CD=TRUE) Quantile estimates from CD-MLE
- remle1 - (if remle=TRUE) Restricted MLE (first constraint)
- qua.remle1 - (if remle=TRUE) Quantile estimates from remle1
- remle2 - (if remle=TRUE) Restricted MLE (second constraint)
- qua.remle2 - (if remle=TRUE) Quantile estimates from remle2
- quant - The quantile probabilities used

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Shin, Y., Shin, Y., & Park, J. S. (2026). Model averaging with mixed criteria for estimating high quantiles of extreme values: Application to heavy rainfall. *Stochastic Environmental Research and Risk Assessment*, 40(2), 47. doi: [10.1007/s0047702503167x](https://doi.org/10.1007/s0047702503167x)

See Also

[glme.gev](#) for stationary GLME estimation, [magev.ksensplot](#) for K sensitivity analysis, [magev.qqplot](#) for Q-Q diagnostic plots, [magev.rlplot](#) for return level plots.

Examples

```
# Load example data
data(haenam)
x <- haenam$X1

# Basic usage with likelihood weights
result <- ma.gev(x, quant = c(0.95, 0.99), weight = 'like1', B = 100)
print(result$qua.ma)      # Model-averaged quantiles
print(result$qua.mle)     # MLE quantiles for comparison
print(result$qua.lme)     # LME quantiles for comparison

# Using generalized L-moment distance weights
result2 <- ma.gev(x, quant = c(0.95, 0.99), weight = 'gLd', B = 100)
print(result2$w.ma)       # Model weights
```

magev.ksensplot	<i>K Sensitivity Plot for MAGEV</i>
-----------------	-------------------------------------

Description

Plots return level estimates, standard errors, and first-order differences across different numbers of candidate submodels K . This helps identify stable regions where estimates converge and select an optimal K value.

Usage

```
magev.ksensplot(
  data = NULL,
  q.cut = 0.6,
  mink = 4,
  maxk = 20,
  quant = c(0.99, 0.995)
)
```

Arguments

data	A numeric vector of data to be fitted (e.g., annual maxima).
q.cut	Quantile cutoff for determining stability (default 0.6).
mink	Minimum number of candidate submodels to test (default 4).
maxk	Maximum number of candidate submodels to test (default 20).
quant	The probabilities for high quantile estimation. Default is c(0.99, 0.995).

Details

The function computes MAGEV estimates for K ranging from `mink` to `maxk`. For each K , it calculates:

- Return level estimates (black points)
- Normalized standard errors (blue line)
- First-order differences (red line with triangles)

The optimal K is selected as the smallest value where both the normalized standard error and first-order difference are below their respective `q.cut` quantile cutoffs. The selected K is indicated by a purple vertical line.

Value

The optimal K value (integer) selected by the algorithm.

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Shin, Y., Shin, Y., & Park, J. S. (2026). Model averaging with mixed criteria for estimating high quantiles of extreme values: Application to heavy rainfall. *Stochastic Environmental Research and Risk Assessment*, 40(2), 47. doi: [10.1007/s0047702503167x](https://doi.org/10.1007/s0047702503167x)

See Also

[ma.gev](#) for the main model averaging function.

Examples

```
data(haenam)
optimal_k <- magev.ksensplot(haenam$X1)
print(optimal_k)
```

`magev.qqplot`

Q-Q Diagnostic Plot for MAGEV

Description

Creates a 2x2 panel of Q-Q plots comparing observed vs. fitted quantiles for different estimation methods: MLE, LME, surrogate (MA), and REMLE.

Usage

```
magev.qqplot(data = NULL, zx = NULL)
```

Arguments

data	A numeric vector of observed data.
zx	A list object returned by ma.gev with remle = TRUE.

Details

The function creates four Q-Q plots:

- Upper left: MLE (Maximum Likelihood Estimation)
- Upper right: LME (L-moment Estimation)
- Lower left: Surrogate MA (Model Averaging surrogate)
- Lower right: REMLE (Restricted MLE, if available)

Points close to the 45-degree diagonal line indicate good model fit.

Value

NULL. The function produces a plot as a side effect.

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Shin, Y., Shin, Y., & Park, J. S. (2026). Model averaging with mixed criteria for estimating high quantiles of extreme values: Application to heavy rainfall. *Stochastic Environmental Research and Risk Assessment*, 40(2), 47. doi: [10.1007/s0047702503167](https://doi.org/10.1007/s0047702503167)

See Also

[ma.gev](#) for the main model averaging function, [magev.rlplot](#) for return level plots.

Examples

```
data(haenam)
qq <- c(seq(0.01, 0.99, by = 0.01), 0.995, 0.999)
zx <- ma.gev(haenam$X1, quant = qq, weight = 'like1',
             numk = 9, varcom = FALSE, remle = TRUE)
magev.qqplot(data = haenam$X1, zx = zx)
```

magev.rlplot	<i>Return Level Plot for MAGEV</i>
--------------	------------------------------------

Description

Displays fitted return levels with 95 return period on a log scale.

Usage

```
magev.rlplot(par = NULL, se.vec = NULL, data = NULL)
```

Arguments

par	A numeric vector of GEV parameters (μ , σ , ξ) in Hosking style. Typically from <code>zx\$surr\$par</code> where <code>zx</code> is the output of ma.gev .
se.vec	A numeric vector of standard errors for the quantile estimates corresponding to the plotting positions. Typically from <code>zx\$ranw.se.ma</code> .
data	A numeric vector of observed data (annual maxima).

Details

The plot shows:

- Black line: Fitted return level curve
- Blue lines: 95
- Black points: Observed data at empirical return periods

The x-axis (return period) is on a log scale, ranging from 0.1 to 900 years.

Value

NULL. The function produces a plot as a side effect.

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Shin, Y., Shin, Y., & Park, J. S. (2026). Model averaging with mixed criteria for estimating high quantiles of extreme values: Application to heavy rainfall. *Stochastic Environmental Research and Risk Assessment*, 40(2), 47. doi: [10.1007/s0047702503167x](https://doi.org/10.1007/s0047702503167x)

See Also

[ma.gev](#) for the main model averaging function, [magev.qqplot](#) for Q-Q diagnostic plots.

Examples

```
data(haenam)
ff <- c(seq(0.01, 0.09, by = 0.01), 0.1, 0.2, 0.3, 0.4, 0.5,
        0.6, 0.7, 0.8, 0.9, 0.93, 0.95, 0.98, 0.99,
        0.993, 0.995, 0.998, 0.999)
zx <- ma.gev(haenam$X1, quant = ff, weight = 'like1',
             numk = 9, varcom = TRUE)
magev.rlplot(par = zx$surr$par, se.vec = zx$ranw.se.ma, data = haenam$X1)
```

MS_pk

*Martins-Stedinger prior function***Description**

Computes the Martins-Stedinger Beta(6,9) prior probability for the GEV shape parameter on the interval $[-0.5, 0.5]$.

Usage

```
MS_pk(para = para, p = 6, q = 9)
```

Arguments

para	A vector of GEV parameters (location, scale, shape).
p	Shape parameter for beta distribution (default 6).
q	Shape parameter for beta distribution (default 9).

Value

Prior probability value (scalar).

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Martins, E. S. & Stedinger, J. R. (2000). Generalized maximum-likelihood generalized extreme-value quantile estimators for hydrologic data. *Water Resources Research*, 36(3), 737-744. doi: [10.1029/1999WR900330](https://doi.org/10.1029/1999WR900330)

See Also

[pk.beta](#) for the adaptive beta penalty, [glme.gev](#) which uses these penalty functions.

Examples

```
# Evaluate MS prior at xi = -0.2
MS_pk(para = c(100, 20, -0.2))
```

nsgev

Non-stationary GEV Parameter Estimation

Description

Estimates parameters of a non-stationary Generalized Extreme Value (GEV) distribution using the L-moment-based algorithm from Shin et al. (2025, J. Korean Stat. Soc.).

This is a convenience wrapper around [lme.gev11](#), providing compatibility with the original nsgev package interface (and with GLmom v1.x).

Usage

```
nsgev(xdat, ntry = 20, ftol = 1e-06)
```

Arguments

xdat	A numeric vector of data to be fitted (e.g., annual maximum values).
ntry	Number of attempts for optimization (default 20).
ftol	Function tolerance for optimization (default 1e-6).

Value

A list containing:

- para.prop - The proposed L-moment based estimates (μ_0 , μ_1 , σ_0 , σ_1 , ξ).
- precis - Precision of the optimization.

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Shin, Y., Shin, Y. & Park, J.-S. (2025). Building nonstationary extreme value model using L-moments. Journal of the Korean Statistical Society, 54, 947-970. doi: [10.1007/s42952025003253](https://doi.org/10.1007/s42952025003253)

See Also

[lme.gev11](#) for the recommended interface, [glme.gev11](#) for the full GLME method with penalty functions, [gado.prop_11](#) for detailed estimation results.

Examples

```
data(PhliuAgromet)
result <- nsgev(PhliuAgromet$prec, ntry = 5)
print(result$para.prop)
```

pargev.kfix

GEV parameter estimation with fixed shape parameter

Description

Estimates GEV location and scale parameters from L-moments while keeping the shape parameter fixed at a user-specified value. Modified from `lmomco::pargev()`.

Usage

```
pargev.kfix(lmom, kfix = 0.1, checklmom = TRUE, ...)
```

Arguments

<code>lmom</code>	L-moments object.
<code>kfix</code>	Fixed shape parameter value.
<code>checklmom</code>	Whether to check L-moment validity.
<code>...</code>	Additional arguments.

Value

A list with components:

type Character "gev"

para Numeric vector of GEV parameters (xi=location, alpha=scale, kappa=shape)

source Character "pargev"

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Hosking, J. R. M. (1990). L-moments: Analysis and estimation of distributions using linear combinations of order statistics. *Journal of the Royal Statistical Society, Series B*, 52(1), 105-124. doi: [10.1111/j.25176161.1990.tb01775.x](https://doi.org/10.1111/j.25176161.1990.tb01775.x)

See Also

[glme.gev](#) for GLME estimation, [pargev](#) for the original L-moment GEV fitting.

Examples

```
data(haenam)
lmom <- lmomco::lmoms(haenam$X1, nmom = 3)
pargev.kfix(lmom, kfix = -0.1)
```

PhliuAgromet	<i>Phliu Agrometeorological Station Data</i>
--------------	--

Description

Annual maximum daily precipitation and station metadata from the Phliu Agrometeorological Station, Chanthaburi province, Thailand (1984-2023). A Mann-Kendall test indicates a significant increasing trend in the annual maxima ($\tau = 0.235$, $p = 0.033$), so this dataset is used for demonstrating non-stationary (GEV11) estimation; it is the heavy rainfall application of Shin et al. (2025).

Usage

```
PhliuAgromet
```

Format

- A data frame with 40 rows and 9 columns:
- Station.ID** Station identifier (character)
 - year** Year of observation (numeric, 1984-2023)
 - prec** Annual maximum daily precipitation in mm (numeric)
 - Name** Station name (character)
 - zone** Climate zone code (character)
 - latitude** Station latitude in degrees (numeric)
 - longitude** Station longitude in degrees (numeric)
 - Starting.year** Record start year (integer)
 - Ending.year** Record end year (numeric)

Source

Phliu Agrometeorological Station, Thailand.

References

Shin, Y., Shin, Y., Park, J., & Park, J. S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi: [10.48550/arXiv.2512.20385](https://doi.org/10.48550/arXiv.2512.20385)

Examples

```
data(PhliuAgromet)
head(PhliuAgromet)

# Fit non-stationary GEV11 model by GLME
result <- glme.gev11(PhliuAgromet$prec, ntry = 5)
print(result$para.glme)
```

pk.beta

Beta preference function for the GEV shape parameter

Description

Computes the data-adaptive Beta preference (penalty) function for the GEV shape parameter, used by both the stationary ([glme.gev](#)) and the non-stationary ([glme.gev11](#)) GLME methods (v2.0.0 unified implementation).

When `q` is `NULL` (adaptive mode), the support is $(\max(-1, \hat{\xi} - c_0), \min(0.3, \hat{\xi} + c_0))$ where $\hat{\xi}$ is `lme.center[3]`, and $q = p + \min(|\hat{\xi}|c_1, c_2)$ for $\hat{\xi} \leq -0.05$ (otherwise $q = p$). When `q` is given (fixed mode), the support is $(\min.xi, \max.xi)$; this mode is used for the fixed literature penalties ("ms", "park", "cannon").

`pk.beta.stnary` is kept as a backward-compatible alias. Note that since v2.0.0 both names use this unified implementation (the v1.x default hyperparameters `c0=0.3`, `c2=5` changed to `c0=0.35`, `c2=2`, and out-of-support values now return `1e-100` instead of `1`).

Usage

```
pk.beta(
  para = NULL,
  lme.center = NULL,
  p = NULL,
  q = NULL,
  min.xi = -1,
  max.xi = 0.5,
  c0 = 0.35,
  c1 = 10,
  c2 = 2
)
```

```
pk.beta.stnary(
  para = NULL,
  lme.center = NULL,
  p = NULL,
  q = NULL,
```

```

    min.xi = -1,
    max.xi = 0.5,
    c0 = 0.35,
    c1 = 10,
    c2 = 2
  )

```

Arguments

<code>para</code>	A vector of GEV parameters; only <code>para[3]</code> (shape) is used.
<code>lme.center</code>	L-moment estimates used as the center (adaptive mode).
<code>p</code>	First shape parameter of the beta distribution.
<code>q</code>	Second shape parameter (optional; if provided, fixed mode is used).
<code>min.xi</code>	Lower support limit in fixed mode (default -1).
<code>max.xi</code>	Upper support limit in fixed mode (default 0.5).
<code>c0</code>	Half-width of the adaptive support (default 0.35).
<code>c1</code>	Scaling hyperparameter for <code>q</code> (default 10).
<code>c2</code>	Upper limit hyperparameter for <code>q</code> (default 2).

Value

A list containing:

- pk.one** Preference function value (scalar)
- p** Shape parameter `p` used
- q** Shape parameter `q` used

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Shin, Y., Shin, Y., Park, J. & Park, J.-S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi: [10.48550/arXiv.2512.20385](https://doi.org/10.48550/arXiv.2512.20385)

See Also

[pk.norm.stnary](#) for the normal penalty, [MS_pk](#) for the Martins-Stedinger penalty, [glme.gev](#), [glme.gev11](#).

Examples

```

# Adaptive beta preference for xi = -0.2 centered at LME xi = -0.15
pk.beta(para = c(100, 20, -0.2),
        lme.center = c(100, 20, -0.15), p = 6, c1 = 3, c2 = 1)

```

pk.norm.stnary	<i>Normal preference function for shape parameter</i>
----------------	---

Description

Computes a normal distribution-based preference (penalty) function value for the GEV shape parameter. The alias `new_pf_norm` is provided for backward compatibility.

Usage

```
pk.norm.stnary(para = NULL, mu = NULL, std = NULL)
```

```
new_pf_norm(para = NULL, mu = NULL, std = NULL)
```

Arguments

<code>para</code>	A vector of GEV parameters.
<code>mu</code>	Mean for normal distribution.
<code>std</code>	Standard deviation for normal distribution.

Value

Preference function value (scalar).

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Shin, Y., Shin, Y., Park, J. & Park, J.-S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi: [10.48550/arXiv.2512.20385](https://doi.org/10.48550/arXiv.2512.20385)

See Also

[pk.beta](#) for the beta penalty, [MS_pk](#) for the Martins-Stedinger penalty, [glme.gev](#) which uses these penalty functions.

Examples

```
# Normal preference with mean=-0.5, sd=0.2 at xi=-0.2
pk.norm.stnary(para = c(100, 20, -0.2), mu = -0.5, std = 0.2)
```

quagev.NS

*Quantile function for non-stationary GEV models***Description**

Calculates quantiles for non-stationary GEV models including GEV11, GEV10, GEV20, and stationary GEV00.

Usage

```
quagev.NS(f = NULL, para = NULL, nsample = NULL, model = NULL)
```

Arguments

f	Probability (or vector of probabilities) for quantile calculation.
para	Parameter vector. For GEV11: (mu0, mu1, sigma0, sigma1, xi).
nsample	Number of time points (sample size).
model	Model type: "gev11", "gev10", "gev20", "gev01", or "gev00"/"gev".

Value

A matrix of quantiles (nsample x length(f)) or a vector if f is scalar.

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Shin, Y., Shin, Y., Park, J. & Park, J.-S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi: [10.48550/arXiv.2512.20385](https://doi.org/10.48550/arXiv.2512.20385)

See Also

[glme.gev11](#) for non-stationary GEV estimation, [glme.gev](#) for stationary GEV estimation, [ran.gev_all](#) for random number generation.

Examples

```
# GEV11 model: time-varying quantiles
para <- c(84.55, 1.03, 2.91, 0.009, -0.08) # mu0, mu1, sigma0, sigma1, xi
q99 <- quagev.NS(f = 0.99, para = para, nsample = 53, model = "gev11")
print(q99)
```

ran.gev_all

Random number generation for non-stationary GEV models

Description

Generates a random sample from a stationary or non-stationary GEV model. For non-stationary models the location and/or scale vary with time $t = 1, \dots, \text{nsample}$: $\mu(t) = \mu_0 + \mu_1 * t + \mu_2 * t^2$ and $\sigma(t) = \exp(\sigma_0 + \sigma_1 * t)$.

Usage

```
ran.gev_all(nsample, para, model = NULL)
```

Arguments

nsample	Sample size (number of time points).
para	Parameter vector; its length and meaning depend on model (see quagev.NS). For "gev11": ($\mu_0, \mu_1, \sigma_0, \sigma_1, \xi$).
model	Model type: "gev", "gev00", "gev01", "gev10", "gev11", or "gev20".

Value

A numeric vector of length nsample.

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

Shin, Y., Shin, Y. & Park, J.-S. (2025). Building nonstationary extreme value model using L-moments. Journal of the Korean Statistical Society, 54, 947-970. doi: [10.1007/s42952025003253](https://doi.org/10.1007/s42952025003253)

See Also

[quagev.NS](#) for the corresponding quantile function, [glme.gev11](#), [lme.gev11](#).

Examples

```
set.seed(1)
# Non-stationary GEV11 sample of size 50
x <- ran.gev_all(50, para = c(100, 0.5, 3, 0.005, -0.2), model = "gev11")
plot(x, type = "l")
```

strup.gev11	<i>Weighted least squares estimation for the non-stationary GEV11 model</i>
-------------	---

Description

Estimates the parameters of the non-stationary GEV11 model by the weighted least squares (WLS) method of Strupczewski and Kaczmarek (2001), with the final-specification modification described in Shin et al. (2025b, JKSS). The result is used as the pre-estimate (starting value) by [glme.gev11](#) and [lme.gev11](#).

Usage

```
strup.gev11(xdat, init.rob = TRUE, wls.rob = FALSE, strup.fin.rob = TRUE)
```

Arguments

xdat	A numeric vector of data to be fitted.
init.rob	If TRUE (default), the initial location trend is fitted by robust regression (lmrob); otherwise by ordinary least squares.
wls.rob	If TRUE, the log-scale regression uses robust regression (default FALSE).
strup.fin.rob	If TRUE (default), the final location trend re-specification uses robust regression.

Value

A list containing:

- strup.para - Original WLS estimates (μ_0 , μ_1 , σ_0 , σ_1 , ξ).
- strup.mdfy - Modified (re-specified) WLS estimates.

Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

References

- Strupczewski, W. G. & Kaczmarek, Z. (2001). Non-stationary approach to at-site flood frequency modelling II. Weighted least squares estimation. *Journal of Hydrology*, 248(1-4), 143-151.
- Shin, Y., Shin, Y. & Park, J.-S. (2025). Building nonstationary extreme value model using L-moments. *Journal of the Korean Statistical Society*, 54, 947-970. doi: [10.1007/s42952025003253](https://doi.org/10.1007/s42952025003253)

See Also

[glme.gev11](#), [lme.gev11](#), [GN16.gev11](#).

Examples

```
data(PhliuAgromet)
result <- strup.gev11(PhliuAgromet$prec)
print(result$strup.mdfy)
```

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